

WELDING ROBOT

# ARCMAN

WELDING SYSTEMS LINEUP



KOBE STEEL, LTD.





## **Examples of the ARCMAN™ being applied for produc tion**

## **CONSTRUCTION MACHINERY**

### Swing Frame - 0



100



Center Frame - 3



Boom - 4





Vertical position weld



Bead appearance 3

- 1 The four manipulators operate in a coordinated manner in order to achieve a significant reduction in welding time.
  - Welding can be performed vertically, thus eliminating the need for positioners and workpiece clamping jigs.
- Our groove-width tracking function compensates for variations in the groove width during welding and regulates the amount of deposited metal in order to achieve high quality welds.

- Tracking the groove width reduces the number of sensing points required.
- 3 Tandem welding reduces the cycle time by about 40% compared to single welding.
  - Controlling the welding conditions for the leading and trailing wires is easy, and ensures smooth surface weld beads and sufficient weld penetration.
  - This is a simple configuration featuring a long arm ARCMAN™ XL robot without slider.
- High efficiency is achieved with a drop-axis positioner, which adopts the optimum welding position for inclined welding lines, together with overhead-suspended tandem welding.
  - This reduces the working space and can be used for both small and large assemblies by traversing between the face plates.

### **BRIDGES AND WATER GATES**

### Bridge and Water Gate - •

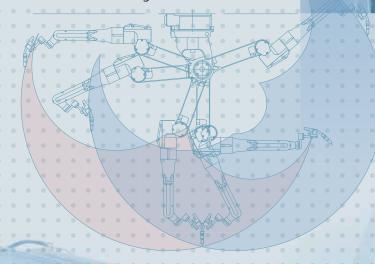


- 5 This configuration employs a long arm robot with a compact carriage, which can handle welding of main girders of widths up to 3 m.
- Two-dimensional CAD data can be converted to three-dimensional data, and teaching data can be created automatically using proprietary software.
- **6** A pair of robots mounted in opposed positions to achieve highly-efficient twin welding. Good-shape weld beads can be achieved even for box welding.
- Functions for monitor-less operation enable continuous automatic welding.

Twin Gantry Type System for Bridge Panel – 3



Bead appearance





## SYSTEMS LINEUP Examples of the ARCMAN™ being applied for production

## **RAILROAD CARS**

### **Truck Parts**



**Truck Frame** 





Vertical position weld appearance



Bead appearance

- High quality, good-shaped weld beads can be achieved with three-dimensional welding lines by employing a see-saw type positioner with cooperative control function and groove-width tracking function.
- With a drop-axis positioner, the vertical motion axis enable the work position to be set lower.
- ARCMAN™ offline Teaching System can efficiently generate teaching data for complicated assemblies.

## **OTHER MACHINERY PARTS**

### **Press Machine/Frame**



- Utilizing three-dimensional CAD data, ARCMAN™ offline Teaching System can easily generate teaching programs for assemblies with particular diversified designs.
- Our compact tandem torch enables multi-pass welding up to maximum depth of 80 mm, thereby significantly reducing the welding time.

### **Forklift Parts/Mast Supports**



- This configuration enables higher efficiency operation of a single system though a pair of opposing positioners.
- The operator can use the positioners semi-automatically to complete a residual welding line whilst the assembly is mounted on the positioner.

### **Standard-Positioner Combined**

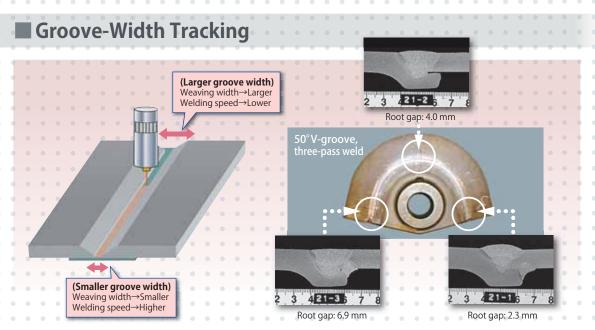


ARCMAN™ MP plus drop-axis two-motion-axis positioner (rotation and tilt



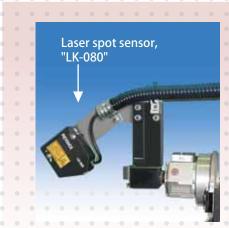


## The ARCMAN™ improves the quality of welding work.



- The weaving width and welding speed can be corrected by detecting real time groove width variations. This reduces the sensing points thereby contributing to cycle time reduction.
- The height of weld reinforcements can be made uniform and the bead width of the cover pass can be regulated.

## ■ Laser Root-Gap Measuring System

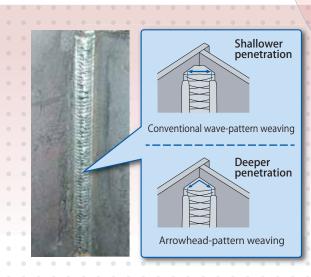


- This function uses a laser to gauge the gap and automatically selects the welding conditions from within the data bank.
- er to gauge ally selects from

  Horizontal fillet

  Single-bevel
- This system selects the lamination technique, determines the wire positioning, and makes the decision on whether or not to weld according to the measured results.

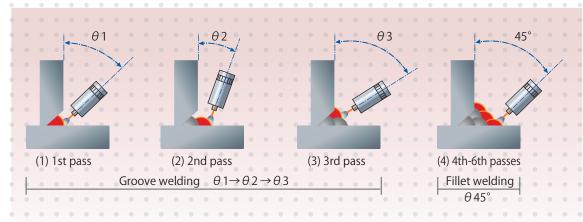
## Arrowhead-Pattern Weaving Function





- This function can be applied for vertical-up welding.
- · This function can be used together with the arc sensor
- This function can also be applied to second passes and beyond in multi-pass welding.

## ■ Data Bank Function and Pass-by-Pass Torch Angle Setting Function

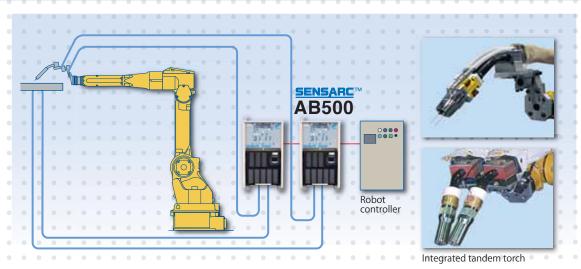


- Up to 499 kinds of welding conditions can be registered.
- This function operates with the teaching points at the weld start and end only, while the optimum torch angle can be set for each pass.



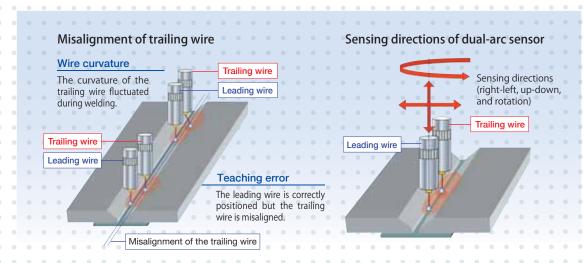
## The ARCMAN™ contributes to reducing the cost of welding work.

## **■** Tandem Arc Welding System



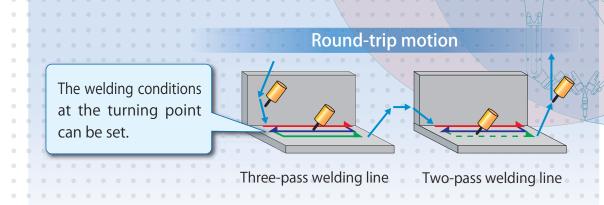
- Automatic select function for welding conditions
   Once the type of groove, plate thickness, or target leg length have been set this function automatically selects the optimum welding parameters.
- Data bank for welding conditions
   Welding conditions for the leading and trailing wires can be verified,
   edited and stored via the data bank screen.

### ■ Dual-arc sensor function



 The dual arc sensor detects changes in the currents of the leading and trailing wires, adjusts misalignments of the leading wire, and corrects misalignments of the trailing wire, as well as function in the same way when the leading and trailing wires are operated in reverse. This improves the weld quality and reduces the need for repair welding.

### ■ Round-Trip Multi-Pass Welding Function



- Since this function performs continuous welding while arc welding is currently being performed, it does not give rise to defects when welding is started or erroneous arc starting. Moreover, since it does away with crater treatment in the middle of arc welding it shortens the time this takes.
- The multi-pass welding, which intermittently performs round-trip horizontal fillet-welding, improves the bead shape because it disperses the weld-start convexity.

### **■** Coordinated Welding Function







- This function synchronizes and coordinates the manipulator and positioner, thereby maintaining a constant welding speed and position
- Maintaining the welding groove in the optimal position improves and stabilizes the weld quality.



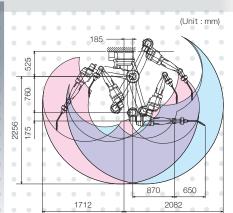


### Model: **ARCMAN™ GS**

#### Features:

- The latest models.
- Features two models with enclosed
- The 1st model with cables enclosed in the upper arm offers the greatest range of motion in its class.
- The 2nd model with cables enclosed in the wrist can perform both single and tandem welding by changing the welding torch.



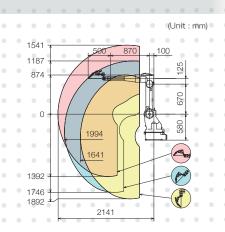


### Model: ARCMAN™ MP

#### **Features:**

· Standard model with state-of-the-art



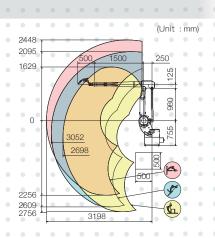


#### Model: ARCMAN™ XL mk II

#### Features:

• Due to its large size and extensive range of motion, the need for a slider may be eliminated, or the size of the slider significantly reduced.



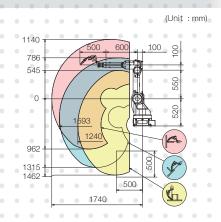


### Model: ARCMAN™ SR

#### **Features:**

 Compact size to cover an extensive work area in conjunction with slider.







### **CA-Type Controller**



• This controller controls the manipulator, positioner, and slider that comprise the

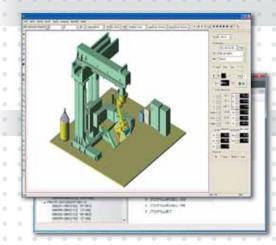
### **Teaching Pendant**



- · Backlit black and white liquid crystal screen that displays 15 rows  $\times$  40 characters
- · Compatible with English and Chinese.

### Specifications for CA-type controller

Items	Specifications
External dimensions and mass	600 (W) × 1100 (H) × 400 (D), 100 kg
Number of controlled axes	Robot: 6 axes, Slider: 3 axes (Optional), Positioner: 2 axes × 2 units (Optional) (11 axes in parallel)
External input/output	Programmable general input: 48 ports, Robot command/interlock input: 57 ports Programmable general output: 48 ports, Robot working mode/status output: 67 ports
Position-detecting function	Absolute encoder
Memory capacity	Equivalent to 46000 steps (with 13 axes configuration), No battery backup is required.
Interface	Ethernet 2 channel.



## **ARCMAN Off-line Teaching System**

- Function for retrieving data from different work mode
- Errors in teaching data can be detected.

### **AP-SUPPORT** (ARCMAN™ Production Support System

#### **Features:**

- Program for production improvement 「productivity weld quality, and takt time.
- Help identify possible causes of stop troubles.
- · Automatically records informations of working data.





#### **SENSARC**<sup>Th</sup>

#### AB500 (designed for robots) High-performance digitallycontrolled welding power source.

- Suitable for medium to thick plate welding with various welding modes.
- Digital control makes maintenance easier.
- Equipped with the extra-low spatter CO2 welding process REGARCTM.



#### **SENSARC™**

#### **LS350D**

Digitally-controlled welding power source featuring extra-low spatter.

- The spatter emission rate can be as low as one-third of conventional inverter-controlled power sources.
- Developed by integrating current-



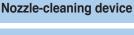
#### **UC500**

High-performance CO<sub>2</sub>/MAG welding power source.

- Unsurpassed performance with instant arc starting.
- Excellent high-speed welding capability.



## Automatic nozzle-changing device





#### Automatic slag-removal device



#### Plasma cutting torch



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**KOBE STEEL, LTD.** http://www.kobelco.co.jp/english/welding/











## **GLOBAL NETWORK**

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#### KOBELCO WELDING OF EUROPE B.V.

Company Profile
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#### KOBE WELDING OF QINGDAO CO., LTD.

Company Profile
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#### KOBE WELDING OF SHANGHAI CO., LTD.

#### **Company Profile**

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#### KOBELCO WELDING INDIA PVT. LTD.

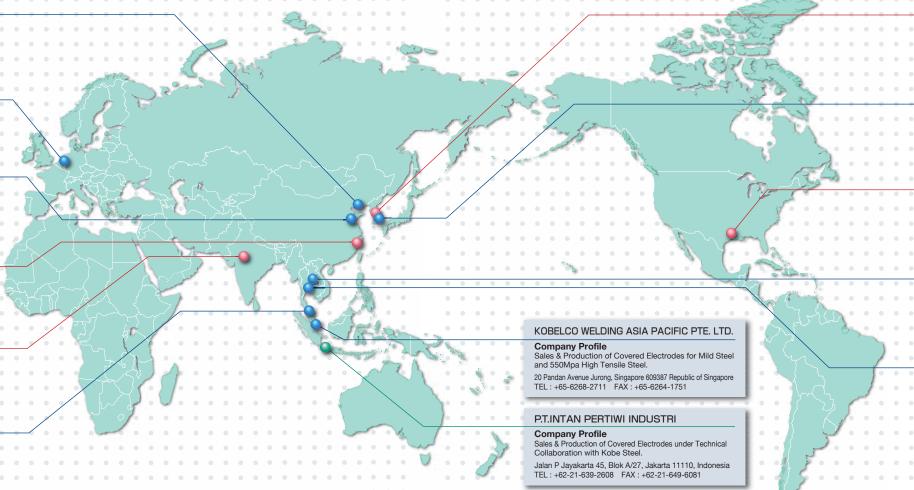
#### **Company Profile**

Sales of Welding consumab

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KOBE WELDING (MALAYSIA) SDN. BHD.

Company Profile
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KOBELCO WELDING MARKETING OF KOREA CO., LTD.

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#### KOBE WELDING OF KOREA CO., LTD.

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#### KOBELCO WELDING OF AMERICA INC.

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#### THAI-KOBE WELDING CO., LTD.

Company Profile
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#### KOBE MIG WIRE(THAILAND)CO., LTD.

#### **Company Profile**

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Production and Sales Bases



Technical Collaboration Partne



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